

# FIBRATIONS OF SPHERES BY GREAT SPHERES OVER DIVISION ALGEBRAS AND THEIR DIFFERENTIABILITY

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## 0. Introduction

Fibrations of  $S^{2n-1}$  by great  $(n-1)$ -spheres arise in the theory of Blaschke manifolds; see Gluck-Warner-Yang [4], in particular §2, p. 1043. Their Theorem B, p. 1041, states that every *differentiable* fibration of this kind is *topologically* equivalent to the fibration of  $S^{2n-1}$  determined by a division algebra. (This division algebra is obtained by a certain linearization process; see Yang [15], Gluck-Warner-Yang [4, §6, p. 1056] and [9, §3, 3.2]. Let us call it the “infinitesimal division algebra”. It should be noted that in general it is neither associative nor alternative.)

Here we answer the natural question: When is the fibration of  $S^{2n-1}$  by great  $(n-1)$ -spheres determined by a division algebra *differentiable* (as a locally trivial fiber bundle)? This turns out to be the case only for the classical Hopf fibrations, which are determined by the classical division algebras  $\mathbf{R}$ ,  $\mathbf{C}$ ,  $\mathbf{H}$  or  $\mathbf{O}$  (see Theorem 1.3 below). This result contradicts Theorem 2 of Yang [15]; his proof contains a fallacy (see [9, 2.10]).

It is possible to construct examples of differentiable fibrations of  $S^{2n-1}$  by great  $(n-1)$ -spheres for which the infinitesimal division algebras are not classical; this shows that the approach of Gluck-Warner-Yang [4] is really only topological (as they point out in Remark 1, p. 1075, without further explanation), and it invalidates Theorem 4 of Yang [15].

However, we still conjecture that every differentiable fibration of  $S^{2n-1}$  by great  $(n-1)$ -spheres is *differentiably* equivalent to the classical Hopf fibration of the same dimension. For  $n = 1, 2$  this is more or less trivially true; for  $n = 4$ , it has been proved in [9]. For the remaining case  $n = 8$ , the problem seems to be open.

The topic of this paper is connected with the theory of topological projective planes; see §2 below and [9, §§1, 2].

## 1. Fibrations determined by division algebras

**1.1. Division algebras.** A (real) division algebra  $D$  of finite dimension  $n$  is a real vector space  $D = \mathbf{R}^n$  equipped with a bilinear multiplication  $(x, y) \mapsto x \cdot y: D^2 \rightarrow D$  which satisfies

(i) every left multiplication map

$$\lambda_a: D \rightarrow D: x \mapsto a \cdot x$$

with  $0 \neq a \in D$  is invertible, i.e.,  $\lambda_a \in \text{GL}_n \mathbf{R}$ .

(ii) there is a "unit element"  $1 \in D$  with  $1 \cdot x = x = x \cdot 1$  for every  $x \in D$ .

Note that the multiplication is not required to be associative or alternative.

As a consequence of (i), every nonzero right multiplication map

$$\rho_a: D \rightarrow D: x \mapsto x \cdot a$$

is invertible as well. We denote the inverse operations by

$$a \setminus b = \lambda_a^{-1}(b) \quad \text{and} \quad b / a = \rho_a^{-1}(b)$$

for  $a, b \in D$  with  $a \neq 0$ ; in other words,  $a \setminus b$  (resp.  $b / a$ ) is the unique solution  $x$  of the equation  $a \cdot x = b$  (resp.  $x \cdot a = b$ ).

The classical examples are, of course,  $\mathbf{R}, \mathbf{C}, \mathbf{H}$  (the quaternions) and  $\mathbf{O}$  (the octonions). But besides these there is a plethora of other real division algebras. For just a few families of examples, cf. Yang [15], [6], [8, 2.6, §3], [7, §4, p. 214]; the latter examples are also found in Benkart-Osborn [1]. See also the references in [5, 7.2].

**1.2. Fibrations determined by division algebras.** Let  $D$  be a real division algebra of dimension  $n$ . Define  $n$ -dimensional subspaces of  $D \oplus D = \mathbf{R}^{2n}$  as follows:

$$U_a = \{(x, a \cdot x) \mid x \in D\} \quad \text{for } a \in D, \quad U_\infty = \{0\} \times D.$$

Then the intersections  $U_a \cap \mathbb{S}^{2n-1}$  for  $a \in D \cup \{\infty\}$  are the fibers of a fibration  $\pi$  of the unit sphere  $\mathbb{S}^{2n-1}$  of  $\mathbf{R}^{2n}$  into great  $(n-1)$ -spheres (we deviate slightly from Yang [15, Theorem 2, p. 580] by interchanging the first and second coordinates). The classical division algebras  $\mathbf{R}, \mathbf{C}, \mathbf{H}$  and  $\mathbf{O}$  lead to the Hopf fibrations.

The fibration  $\pi$  obtained in this way from any division algebra  $D$  is always a topological locally trivial fiber bundle (see the proof of Proposition 2.5 in [9]). Here we are concerned with the question: When is  $\pi$  a *differentiable* fiber bundle? Theorem 2 of Yang [15] asserts that this is always the case. This assertion is drastically refuted by Theorem 1.3 below (for the fallacy in Yang's proof see [9, 2.10]), which means that from the multitude of finite-dimensional real division algebras, a differentiable fiber bundle is obtained only in the classical cases:

**1.3. Theorem.** *The fibration  $\pi$  determined by a real division algebra  $D$  of finite dimension is a differentiable locally trivial fiber bundle if and only if  $D$  is isomorphic to  $\mathbf{R}, \mathbf{C}, \mathbf{H}$  or  $\mathbf{O}$ .*

*Proof.* The Hopf fibrations are known to be differentiable locally trivial fiber bundles. Conversely, assume  $\pi$  to be differentiable. We use the differentiability criterion given in [9, 2.5] for arbitrary fibrations of  $S^{2n-1}$  by great  $(n - 1)$ -spheres (not necessarily determined by division algebras). It states that the map

$$\bar{\gamma} : D \times (D \setminus \{0\}) \rightarrow \text{End}_{\mathbf{R}}(D) : (x, y) \mapsto \begin{cases} \lambda_{y/x}^{-1} & \text{for } x \neq 0, \\ 0 & \text{for } x = 0 \end{cases}$$

must be differentiable (even at  $x = 0$ ). In particular, for every fixed vector  $v \neq 0$  the map

$$\bar{\gamma}_v : D \rightarrow \text{End}_{\mathbf{R}}(D) : x \mapsto \begin{cases} \lambda_{v/x}^{-1} & \text{for } x \neq 0, \\ 0 & \text{for } x = 0 \end{cases}$$

is differentiable, with differential  $d_0 \bar{\gamma}_v$  at  $x = 0$ . For  $t \in \mathbf{R} \setminus \{0\}$  and  $v, x \in D$  with  $x \neq 0$ , bilinearity of the multiplication implies  $v/(tx) = t^{-1}(v/x)$ , hence  $\lambda_{v/(tx)} = t^{-1} \lambda_{v/x}$  and  $\lambda_{v/(tx)}^{-1} = t \lambda_{v/x}^{-1}$ . This yields

$$\begin{aligned} d_0 \bar{\gamma}_v(x) &= \left. \frac{d}{dt} \bar{\gamma}_v(tx) \right|_{t=0} = \left. \frac{d}{dt} \lambda_{v/(tx)}^{-1} \right|_{t=0} \\ &= \left. \frac{d}{dt} (t \lambda_{v/x}^{-1}) \right|_{t=0} = \lambda_{v/x}^{-1} = \bar{\gamma}_v(x). \end{aligned}$$

Thus  $\bar{\gamma}_v$  is linear, by the linearity of a differential, and

$$x \mapsto \bar{\gamma}_v(x)(z) = \begin{cases} (v/x) \setminus z & \text{for } x \neq 0, \\ 0 & \text{for } x = 0 \end{cases}$$

is a linear endomorphism of  $D = \mathbf{R}^n$  for every  $z \in D$ . In other words we have obtained the identity

$$(v/(x + x')) \setminus z = (v/x) \setminus z + (v/x') \setminus z,$$

which holds for  $v, x, x', z \in D$  with  $v, x, x', x + x'$  all distinct from zero. Now the proof is completed by the following lemma, which requires only the special case  $x' = 1, v = x + 1 = (1 + 1/x) \cdot x$  (and hence  $v/x = 1 + 1/x$ ) of the identity above.

**1.4. Lemma.** *Let  $D$  be a real finite-dimensional division algebra which satisfies the identity*

$$z = (1 + 1/x) \setminus z + (x + 1) \setminus z$$

for  $x, z \in D, x \neq 0, -1$ . Then  $D$  is isomorphic to  $\mathbf{R}, \mathbf{C}, \mathbf{H}$  or  $\mathbf{O}$ .

*Proof.* Replacing  $z$  by  $(x + 1) \cdot z$  gives

$$x \cdot z + z = (x + 1) \cdot z = (1 + 1/x) \setminus (x \cdot z + z) + z,$$

hence  $x \cdot z = (1 + 1/x) \setminus (x \cdot z + z)$ , which is equivalent to  $(1 + 1/x) \cdot (x \cdot z) = x \cdot z + z$ . This yields  $(1/x) \cdot (x \cdot z) = z$ , i.e.,  $D$  has the left inverse property (cf. Hughes-Piper [10, p. 135] or Pickert [12, p. 106]; note that the special case  $x \cdot z = 1$  shows  $1/x = x \setminus 1$ ). By a result of Skornyakov-San Soucie (see Hughes-Piper [10, Theorem 6.16, p. 140] or Pickert [12, 6.16, p. 182]),  $D$  is an alternative division algebra, hence isomorphic to  $\mathbf{R}, \mathbf{C}, \mathbf{H}$ , or  $\mathbf{O}$  by well-known theorems of Frobenius (cf. Palais [11] or Ebbinghaus et al. [3, p. 161]) and Zorn [16] (cf. also Ebbinghaus et al. [3, p. 178] or Pickert [12, p. 177]).

## 2. Differentiable projective planes over division algebras

**2.1.** A *differentiable projective plane* is a projective plane whose point set  $P$  and line set  $\mathcal{L}$  are endowed with the structure of a differentiable manifold of positive dimension such that the points on a fixed line and dually the pencil of lines through a fixed point form submanifolds and such that the operations  $\vee$  and  $\wedge$  of joining distinct points and intersecting distinct lines are differentiable; cf. Breitsprecher [2]. We shall consider lines as subsets of the point set (by identification with the set of incident points).

It is a conjecture of Betten that the four classical planes over  $\mathbf{R}, \mathbf{C}, \mathbf{H}, \mathbf{O}$  are the only differentiable projective planes; here we establish a special case of this conjecture.

**2.2. Theorem.** *The only differentiable projective planes which are translation planes as well as dual translation planes are the classical projective planes over  $\mathbf{R}, \mathbf{C}, \mathbf{H}$  and  $\mathbf{O}$ .*

**2.3. Explanations.** A projective plane is called a *translation plane* if there is a line  $L$  such that the group of all translations with axis  $L$  acts

transitively on the points not on  $L$ ; the line  $L$  is then called a “translation line”. The dual condition, i.e., the existence of a “translation point”, characterizes the dual translation planes. The projective planes which are translation planes as well as dual translation planes are known as the planes of Lenz-type (at least)  $V$  (cf. Pickert [12, 3.14, p. 70]); these are precisely the planes which can be coordinatized by (nonassociative) division rings; see below.

*Proof of Theorem 2.2.* Let  $L$  be a translation line. If some point not on  $L$  is a translation point, then every point is a translation point; cf. Hughes-Piper [10, Theorem 4.20, p. 101]. Hence we may assume that we have a translation point  $v$  on  $L$ . We pick points  $o, u, e$  such that  $o, u, v, e$  form a nondegenerate quadrangle with  $L = u \vee v$ , and we put

$$w = (o \vee e) \wedge L.$$

Coordinatization of the plane with respect to  $o, u, v, e$  amounts to the following: On  $D := (o \vee e) \setminus \{w\}$  we define an addition and a multiplication by

$$\begin{aligned} x + y &:= ((xu \wedge ov)w \wedge yv)u \wedge oe, \\ x \cdot y &:= ((xu \wedge ev)o \wedge yv)u \wedge oe, \end{aligned}$$

for  $x, y \in D$ ; here we have used the abbreviation  $xu = x \vee u$  for the line joining  $x$  and  $u$ . Then  $(D, +, \cdot)$  is a (nonassociative) division ring, or, in other terminology, a semifield; see Hughes-Piper [10, Theorem 6.9, p. 134] or Pickert [12, 3.3.8 and 3.3.9, p. 101] or Stevenson [14, 13.2.1, p. 372]. In particular,  $(D, +)$  is an abelian group, and for  $a \in D \setminus \{0\}$  the left and right multiplication maps  $\lambda_a = (x \mapsto a \cdot x)$  and  $\rho_a = (x \mapsto x \cdot a)$  are automorphisms of  $(D, +)$  (this expresses the distributivity and divisibility properties of the multiplication).

Differentiability of join and intersection implies that the algebraic operations of  $D$  and their inverses are differentiable. In particular,  $(D, +)$  is an abelian Lie group, and  $(D, +) \cong (\mathbb{R}^n, +)$  for some natural number  $n$  (cf. also Salzmann [13, 7.23]) since the left multiplications  $\lambda_a$  with  $0 \neq a \in D$  form a transitive set of automorphisms. By continuity, the automorphisms  $\lambda_a$  and  $\rho_a$  are  $\mathbb{R}$ -linear, and the multiplication is  $\mathbb{R}$ -bilinear. Hence  $D$  is a real division algebra as defined in 1.1.

The point set  $A$  of the affine plane with  $L$  as the line at infinity is identified with  $D \oplus D = \mathbb{R}^{2n}$  by mapping a point  $p$  not on  $L$  onto the pair  $(pv \wedge oe, pu \wedge oe)$ . The lines of the affine plane are then just the subspaces  $U_a, a \in D \cup \{\infty\}$ , as in 1.2 together with their cosets in  $D \oplus D = \mathbb{R}^{2n}$ .

From this point on we indicate two ways to prove Theorem 2.2. The first one involves the fibration determined by  $D$ . The map

$$\pi: A \setminus \{o\} \rightarrow L: p \mapsto po \wedge L$$

is the projection map of a differentiable fiber bundle whose fibers are the subsets  $U_a \setminus \{0\} \cong D \setminus \{0\} \cong \mathbb{R}^n \setminus \{0\}$  for  $a \in D \cup \{\infty\}$ ; local trivializations are given by

$$\begin{aligned} A \setminus U_0 &\rightarrow (L \setminus \{u\}) \times (D \setminus \{0\}) \\ p &\mapsto (po \wedge L, pu \wedge oe) \end{aligned}$$

and

$$\begin{aligned} A \setminus U_\infty &\rightarrow (L \setminus \{v\}) \times (D \setminus \{0\}) \\ p &\mapsto (po \wedge L, pv \wedge oe). \end{aligned}$$

In our coordinates, with  $A$  identified with  $D \oplus D$ , these trivializations are just the maps  $(x, y) \mapsto (\pi(x, y), y)$  and  $(x, y) \mapsto (\pi(x, y), x)$ .

We now consider the restriction of  $\pi$  to the unit sphere  $\mathbb{S}^{2n-1}$  of  $A = \mathbb{R}^{2n}$ , i.e., the map

$$\pi: \mathbb{S}^{2n-1} \rightarrow L: p \mapsto po \wedge L.$$

The fibers of this restriction are the subsets  $U_a \cap \mathbb{S}^{2n-1} \cong \mathbb{S}^{n-1}$ ; thus we get precisely the fibration of  $\mathbb{S}^{2n-1}$  determined by the division algebra  $D$  according to 1.2. Local trivializations for this restriction are obtained by appending the radial projection of  $D \setminus \{0\} \cong \mathbb{R}^n \setminus \{0\}$  onto  $\mathbb{S}^{n-1}$  to the local trivializations above, so we still have a differentiable fiber bundle. Therefore the assertion of Theorem 2.2 follows from Theorem 1.3.

(We remark that the trivializations in Yang [15, Theorem 2] can be obtained as an algebraic transcription of these simple geometric ideas; see [9, 2.9].)

The second (more direct) approach is based on the following geometric calculation using our identification of the affine plane with  $D \oplus D$ : for  $x, y, z \in D$  with  $y \neq 0$  we have

$$((x, y) \vee (0, 0)) \wedge ((0, z) \vee u) = U_{y/x} \wedge (D \times \{z\}) = (\lambda_{y/x}^{-1}(z), z)$$

if  $x \neq 0$ , and

$$((0, y) \vee (0, 0)) \wedge ((0, z) \vee u) = U_\infty \wedge (D \times \{z\}) = (0, z).$$

Hence differentiability of join and intersection implies that the map  $\bar{\gamma}$  in the proof of Theorem 1.3 is differentiable, and we can proceed as in that proof.

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